

# Efficient Model Checking for *Circus* Using FDR

26th May 2015

# Introduction

## Aims

- Introduce Model Checking
- Talk about efficient Model Checking for *Circus*...

## Topics

- 1 Model Checking Overview
- 2 FDR Introduction
- 3 *Circus* Introduction
- 4 Model Checking Problems

## Thanks

- Alvaro Miyazawa
- Tom Gibson-Robinson (Oxford)

# Model Checking

## What is Model Checking?

- Technique for verifying concurrent systems
- Determines if  $M$  is a model for a formula  $f$ 
  - $M$  is a transition system
  - $f$  is a temporal logic specification
- That is,  $M$  exhibits whatever property  $f$  captures
- In traditional Model Checking,  $M$  and  $f$  are written in different languages

# Model Checking

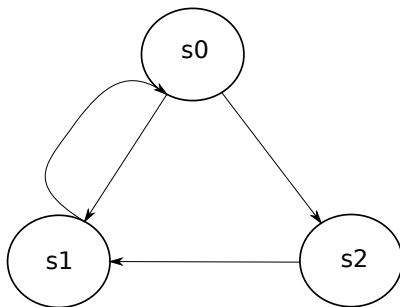
## Temporal Logic

- In temporal logic a formula has dynamic truth
  - A formula can be true for some of a system's states. . .
  - But false for others
- Usually has operators to specify. . .
  - What happens next
  - What happens sometime in the future
  - Something that happens for all future states
  - And logic operators like negation, conjunction and disjunction

# Model Checking

## Transition Systems

- Model a system using...
  - States (static structure)
  - Transitions (dynamic structure)
- Finite transition systems can be expressed as directed graphs



# Model Checking

## Advantages

- No need to write proofs...
  - Although the model and the specification are needed
- Automatic...
  - After the model and specification are written
- Concurrency errors...
  - Difficult to reproduce with testing
- Fast...
  - Compared to other rigorous methods, like proof checking
- Counterexamples...
  - Invaluable for debugging

# Model Checking

## Disadvantages

- Finite state. . .
  - Automation generally requires finite state systems
- State Explosion. . .
  - Can be a big problem, most of the problems we address are due to this

# Failures-Divergences Refinement

## FDR

- Model Checking tool. . .
  - Although it's really a refinement checker
- Model and the specification are the same language. . .
  - CSP<sub>M</sub>, the machine-readable version of CSP
- Performing a check. . .
  - **Compile** both CSP processes into Labelled Transition Systems
  - **Check** if one is a refinement of the other



# Failures-Divergences Refinement

## Refinement

- Is a model an implementation of a specification?
- $P \sqsubseteq Q$  if every behaviour of  $Q$  is also a behaviour of  $P$ 
  - $Q$  exhibits the property captured by  $P$
  - $Q$  implements  $P$

## Semantic Models

- Traces refinement  $\sqsubseteq_T \dots$ 
  - $P \sqsubseteq_T Q$  if every trace of  $Q$  is a trace of  $P$
- Failures Refinement  $\sqsubseteq_F \dots$ 
  - Failure: a trace leading to events that may be refused
- Failures-Divergences Refinement  $\sqsubseteq_{FD} \dots$ 
  - Divergence: a trace leading to undefined behaviour

# *Circus* and CSP<sub>m</sub> Introduction

## *Circus*

- Combines...
  - CSP to capture Behaviour
  - Z to capture Data
- Variants...
  - Object Orientation – Oh*Circus*
  - Time – *CircusTime*
- Model Checking in FDR...
  - Requires translation to CSP<sub>m</sub>
  - Different capabilities...

# Circus and CSP<sub>m</sub> Introduction

## CSP<sub>m</sub>

- Events...
  - Model important points in the history of the system
  - May communicate parameters ( $c!x$  or  $c?x$  or simply  $c.x$ )
  - Parameters can be restricted to certain values ( $c?x:set$ )
  - Sequenced using prefix ( $c \rightarrow P$ )
  - May be guarded by a predicate ( $(guard) \& c \rightarrow P$ )
- Processes in...
  - External choice ( $P \square Q$ )
  - Interleaving ( $P \parallel Q$ )
  - Parallel ( $P \parallel [X] Q$ )
  - Sequence ( $P ; Q$ )
- Replication (e.g.  $\parallel s : set @ P(s)$ )

# Model Checking Problems

## Problem Classes

- Data...
  - FDR struggles with...
    - Large data-types
    - Processes holding several unrelated parameters of large data-types
    - Infinite types
- Structure...
  - FDR struggles with...
    - Large numbers of states
    - Large orderings of processes from parallelisms

# Model Checking Problems

## Data Problems

- *Circus* has variables but CSP does not. . .
  - To represent variables in CSP we use processes to control variables
  - e.g.  $P(\text{num})$  to control the variable `num`
- FDR evaluates and compiles all possible combinations of states
- Strive to reduce the state space in the model. . .

# Data Problems

## Reducing State Space

- Bound large types
  - For example  $\{0..50\}$
- Use direct function calls to pass large parameters, if possible...
  - Uses the functional language elements of CSPm
  - e.g instead of accumulating the set with  
 $P(\text{set}) = \text{add?x} \rightarrow P(\text{union}(\text{set}, x))\dots$
  - Call  $P(\{1..100\})$  to directly pass the set
- Refactor processes that control large state variables into many smaller processes in interleaving...

# Data Example One

## Use Case

- Model contains a set of data of type value
- We can put values in and take values out
- Attempting to put the same value in twice is not possible

# Data Example One

## Process Controlling a Set: Bad

```
P1(set) =  
  in?x:set -> P1(set)  
  []  
  in?x:diff(value,set) -> P1(union(set, x))  
  []  
  out?x:set -> P1(diff(set, x))
```



# Data Example One

## Process Controlling a Set: Good

```
P2 = ||| x : value @ NotMember(x)
```

```
NotMember(x) =  
  in.x -> Member(x)
```

```
Member(x) =  
  in.x -> Member(x)  
  []  
  out.x -> NotMember(x)
```

# Data Example One

## Comparison

- Since both processes can only add the same number to the set once, they are equivalent. . .
  - $P_1 \sqsubseteq_T P_2$  and  $P_2 \sqsubseteq_T P_1$
  - $P_1 \sqsubseteq_F P_2$  and  $P_2 \sqsubseteq_F P_1$
  - $P_1 \sqsubseteq_{FD} P_2$  and  $P_2 \sqsubseteq_{FD} P_1$

## Data Example One

## Deadlock Freedom Check

		value=			
		{0..5}	{0..10}	{0..15}	{0..20}
$P_1$	Compiled	0.02s	0.69s	39.57s	7438.52s <sup>1</sup>
	Checked	0.04	0.02s	0.12s	3.84s
$P_2$	Compiled	0.01s	0.01s	0.01s	0.01s
	Checked	0.06s	0.08s	0.23s	4.41s

~ 2 hours

# Data Example One

## Explanation

- $P_1$  takes longer to compile than  $P_2$  but  $P_2$  takes longer to check
- There is a trade-off between the compilation time of a set and the checking time of many interleaved actions
  - Checking phase can be more easily parallelised

## Data Example Two

### Use Case

- Model contains a sequence representing a stack
- We can push and pop a value, and check the top element
- We cannot push more than a max number of values
- We cannot pop a value or check the top value of an empty stack

## Data Example Two

### Process Controlling a Sequence: Bad

```
Q1(sequence) =  
  (#sequence < maxStackId) &  
    push?x ->  
      Q1(<x>^sequence)  
  []  
  (not null(sequence)) &  
  (  
    pop ->  
      Q1(tail(sequence))  
    []  
    top!head(sequence) ->  
      Q1(sequence)  
  )
```

## Data Example Two

### Process Controlling a Sequence: Good

```
Q2 =  
  (|| i : value @ [ AlphaFree(i) ]  
    Free(i)  
  ) \{| resume|}
```

## Data Example Two

### Process Controlling a Sequence: Good

```
Free(id) = push.id?v -> Full(id, v)
```

```
Full(id, v) =
```

```
  pop.id-> (if id > minStackId then  
            resume.id-1 -> Free(id)
```

```
            else
```

```
              Free(id))
```

```
  []
```

```
  (id < maxStackId) &
```

```
    push.id+1?_ -> resume.id -> Full(id, v)
```

```
  []
```

```
  top.id!v -> Full(id, v)
```



## Data Example Two

### Comparison

- Since this is only a change of structure (once we apply renaming to  $Q_2$ ) these processes are equivalent. . .
  - $Q_1 \sqsubseteq_T Q_2$  and  $Q_2 \sqsubseteq_T Q_1$
  - $Q_1 \sqsubseteq_F Q_2$  and  $Q_2 \sqsubseteq_F Q_1$
  - $Q_1 \sqsubseteq_{FD} Q_2$  and  $Q_2 \sqsubseteq_{FD} Q_1$

## Data Example Two

## Deadlock Freedom check

		value=			
		{0..5}	{0..6}	{0..7}	{0..8}
$Q_1$	Compiled	0.82s	13.92s	417.83s	21462.05 <sup>2</sup>
	Checked	0.02s	0.07s	0.99s	N/A <sup>3</sup>
$Q_2$	Compiled	0.02s	0.02s	0.03s	0.03s
	Checked	0.09s	0.14s	0.89s	18.57s

---

<sup>2</sup>~ 5.9 hours

<sup>3</sup>FDR crashed...

## Data Example Two

### Explanation

- $Q_1$  compiles slower due to checking the length of the sequence
- $Q_2$  compiles faster because each process only controls one variable
- Trade-off in terms of checking. . .
  - $Q_1$  controls a sequence, but is sequential
  - $Q_2$ 's sub-processes only control one variable each but being are parallel

# Process Structure Problems

## Large Possible Orderings of Behaviour

- FDR explores all the possible states
  - Before any hiding or parallel restrictions can occur
- This can cause FDR to use a lot of memory

# Structure Example One

## Use Case

- Waiting for many subordinate processes to signal readiness. . .
- Which may happen in any order

# Structure Example One

For a process...

```
R(x) = ready.x -> SKIP
```

Simple Replicated Interleave...

```
Interleave = ||| x : value @ R(x)
```

... Becomes Replicated Sequential Composition

```
Sequential = ; x : seq(value) @ R(x)
```

# Structure Example One

## Comparison

- *Interleave*  $\sqsubseteq_T$  *Sequential* but not the other way around...
  - Because *Interleave* can perform `ready.x` events in any order, whereas in *Sequential* the order is fixed
- Refinement does not hold in any other semantic models
- *Sequential* can be said to implement *Interleave*

## Structure Example One

## Deadlock Freedom check

		value=			
		{0..15}	{0..20}	{0..25}	{0..30}
<i>Intr</i>	Compiled	0.01s	0.01s	0.01s	0.01s
	Checked	0.17s	1.99s	77.34s	3455.14s <sup>4</sup>
<i>Seq</i>	Compiled	0.00s	0.00s	0.01s	0.01s
	Checked	0.05s	0.05s	0.04s	0.05s



# Structure Example One

## Explanation

- $R(x)$  is a simple process so both versions are fast
- *Interleave* is slower to check because the events may happen in any order
- *Sequential* is much quicker because FDR chooses an arbitrary order for the events to happen in
- However, these processes are not equivalent

# Summary

## Model Checking

- Verification technique useful for concurrent systems
- Usually automatic and quick
- However, has some general limitations
  - State explosion being the most common

# Summary

## Efficient Model Checking in FDR

- Problems can occur when using data or parallelism yield a large number of state
- Solutions. . .
  - Use the functional elements of CSP<sub>M</sub>
  - Refactor processes controlling variables
  - Possibly refactor interleavings
- Mileage may vary. . .